

Topological contact toric manifolds

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(joint work with S. Sarkar)
arXiv:1909.00994 [math.AT]

School of Mathematical, KIAS

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(Workshop for Young Researchers)
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Questions

Given two topological spaces X_1 and X_2 ...

Cohomological rigidity

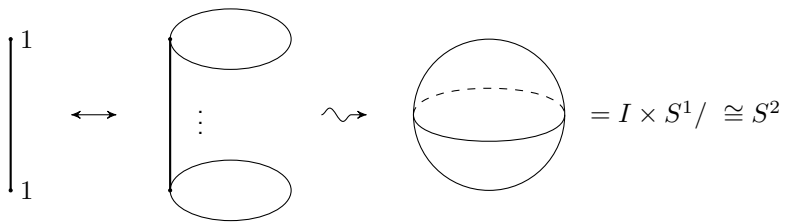
$$H^*(X_1) \cong H^*(X_2) \xrightarrow{?} \exists f: X_1 \xrightarrow{\cong} X_2$$

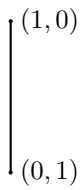
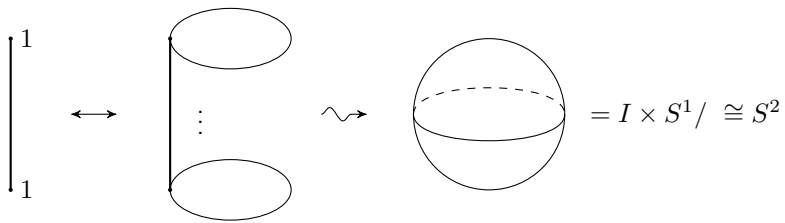
If both X_1 and X_2 are equipped with G -actions...

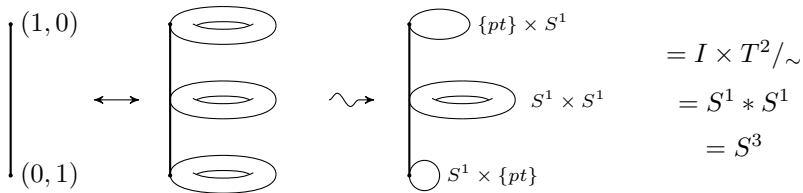
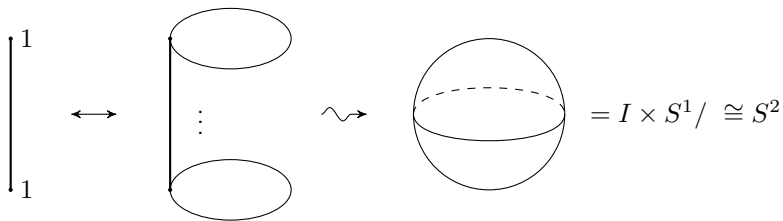
Equivariant Cohomological Rigidity

$$H_G^*(X_1) \cong H_G^*(X_2) \xrightarrow{?} \begin{array}{ccc} G \times X_1 & \xrightarrow[\cong]{\theta \times f} & G \times X_2 \\ \downarrow & \circlearrowleft & \downarrow \\ X_1 & \xrightarrow[\cong]{f} & X_2 \end{array}$$

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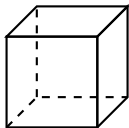




Objects (by examples)

$$T^3 \curvearrowright X^6$$

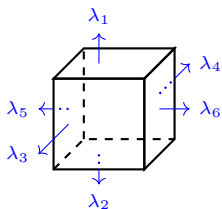
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$$F_i \mapsto \lambda_i$$

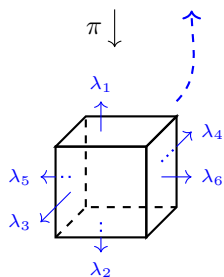
such that

$\{\lambda_i, \lambda_j, \lambda_k\}$: \mathbb{Z} -basis of \mathbb{Z}^3 ,

whenever $F_i \cap F_j \cap F_k \neq \emptyset$.

Objects (by examples)

$$T^3 \curvearrowright X^6 \cong (P^3 \times T^3)/\sim$$



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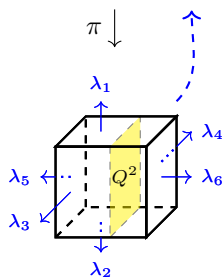
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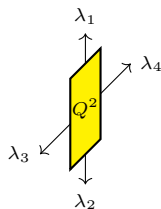
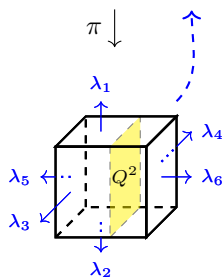
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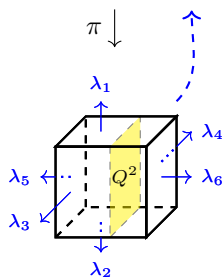
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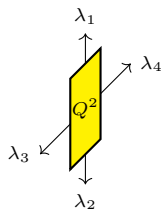
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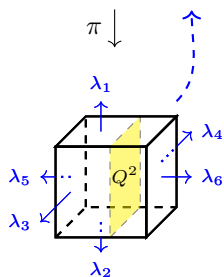
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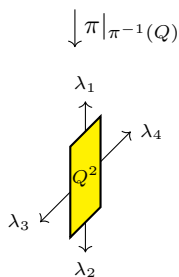
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Constructive definition

- ▶ Q^n : n -dimensional simple polytope,
- ▶ $\lambda: \mathcal{F}(Q^n) \rightarrow \mathbb{Z}^{n+1}$ such that $\text{span}_{\mathbb{Z}}\{\lambda(F_{i_1}), \dots, \lambda(F_{i_k})\}$: direct summand of \mathbb{Z}^{n+1} , whenever $F_{i_1} \cap \dots \cap F_{i_\ell} \neq \emptyset$.

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Axiomatic definition

A smooth manifold X^{n+k} with effective T^k -action s.t.

- ▶ locally isomorphic to $T^n \times T^{k-n} \curvearrowright \mathbb{C}^n \times T^{k-n}$,
- ▶ X^{n+k} / T^k is homeomorphic to a simple polytope P^n as manifold with corners.

Examples

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$$\begin{cases} \lambda(F_i) = e_i & i = 1, \dots, n \\ \lambda(F_{n+1}) = (-q_1, \dots, -q_n, p) & \gcd(q_1, p) = \dots = \gcd(q_n, p) = 1, \end{cases}$$

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$k = n + 2$, hyperplane cut of t.c.t.m.

\vdots

Contact toric manifolds

Definition (Contact toric manifold)

A $(2n + 1)$ -dimensional contact manifold M with an effective T^{n+1} -action preserving the contact structure.

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Theorem [Lerman, 2002] The classification of c.c.c.t.

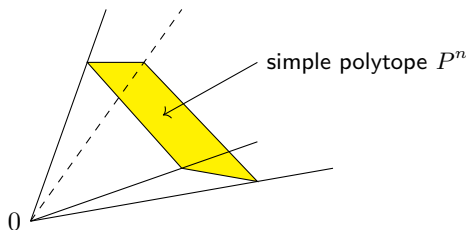
	$T^{n+1} \curvearrowright M$ freely	$T^{n+1} \curvearrowright M$ not freely
$\dim M = 3$	T^3	Lens space
$\dim M > 3$	Principal T^{n+1} -bundle over S^n	Classified by moment cone.

Moment cone

- ▶ (M, α) : contact G -manifold,
- ▶ $(M \times \mathbb{R}, d(e^t \alpha))$: symplectization of (M, α) ,
- ▶ $G \curvearrowright M \times \mathbb{R}$, (trivially on \mathbb{R} .)
- ▶ $\Phi: M \times \mathbb{R} \rightarrow \mathfrak{g}^*$ moment map.

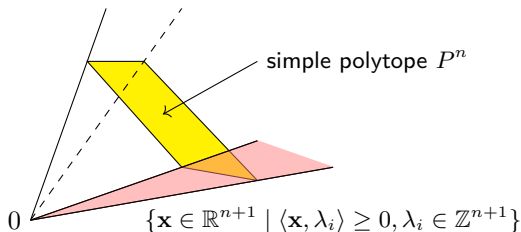
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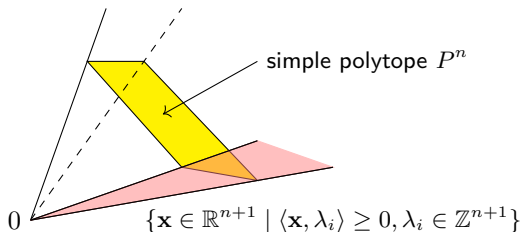
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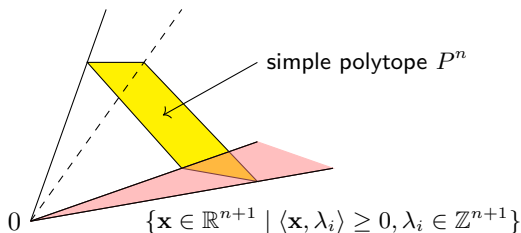
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- ▶ $M \cong P^n \times T^{n+1} / \sim$, (T^{n+1} -equivariantly homeomorphic.)

Answer for the equivariant cohomological rigidity

For $T^{n+k} \curvearrowright X_1^{n+k}$ and $T^{n+k} \curvearrowright X_2^{n+k}$,

(1) When $k = n$:

Theorem (Masuda, 2008)

X_1, X_2 : quasitoric manifolds.

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(2) When $k = m$ and $\lambda: \mathcal{F}(Q) \rightarrow \mathbb{Z}^m$ is given by $F_i \mapsto e_i$:

Theorem (Davis–Januszkiewicz, 1991)

$H_{T^m}^*(\mathcal{Z}_Q) \cong \text{SR}[Q]$ ring isom.

(3) When $k = n + 1$,

Theorem (Sarkar-S, 2019, arXiv)

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«Thank you for your attention.»