

# A Carleman estimate for an elliptic operator with a discontinuous coefficient in a partially anisotropic media

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## Abstract

We prove a Carleman estimate for the elliptic operator  $A = -\nabla \cdot (B\nabla)$  with an arbitrary observation region. The structure of the  $n \times n$  matrix  $B$  gives the partially anisotropic character: a block diagonal matrix in which the first block is the product of a  $(n-1) \times (n-1)$  hermitian matrix  $C_\tau$  by a scalar function  $x_n \rightarrow a(x_n)$  and the second block  $c$  is a positive function. The coefficients of the matrix  $C_\tau$  are  $\mathcal{C}^1$  and  $a, c$  are piecewise  $\mathcal{C}^1$  in  $\bar{\Omega}$ , a bounded connected domain of  $\mathbb{R}^n$ . If  $S$  denotes the set where discontinuities of  $c$  can occur, we suppose that  $\Omega$  is stratified in a neighborhood of  $S$  in the sense that locally it takes the form  $\Omega_\delta := \Omega' \times (-\delta, \delta)$  with  $\Omega' \subset \mathbb{R}^{n-1}$ ,  $\delta > 0$  and  $S = \Omega' \times \{0\}$ . This Carleman estimate is obtained through the introduction of a suitable mesh of  $\Omega_\delta$  and an associated approximation of  $B$  involving the Carleman large parameters.

We shall give some extensions of the used method and explain how a local estimate makes us able of writing a global estimate.

## 1 Notations and result

We consider the positive selfadjoint elliptic operator:  $D(A) = \{u \in H_0^1(\Omega); \nabla \cdot (B\nabla u) \in L^2(\Omega)\}$ ,  $A = -\nabla \cdot B\nabla$ , where for the simplicity we assume  $\Omega$  is the bounded open set  $\Omega = \Omega' \times (-H, H) \subset \mathbb{R}^{n-1} \times \mathbb{R}$ . We suppose

- the interface  $S := \{x = (x', 0); x' \in \Omega'\}$  is a  $\mathcal{C}^2$  open set;
- the  $n \times n$  symmetric real matrix  $B$  has the form

$$B(x) = \begin{pmatrix} a(x_n)C_\tau(x) & 0 \\ 0 & c(x) \end{pmatrix}; \quad (1)$$

- the function  $x_n \rightarrow a(x_n)$  is  $\mathcal{C}^1$  on  $[-H, 0]$  and  $[0, H]$ , the scalar function  $x \rightarrow c(x)$  is  $\mathcal{C}^1$  on the closure of the two open sets  $\Omega^\pm = \{x \in \Omega; \pm x_n > 0\}$ , its two restrictions  $x' \rightarrow c_\pm(x') := c(x', 0^\pm)$  to the interface  $S$  being  $\mathcal{C}^2$ , whereas the coefficients of the  $(n-1) \times (n-1)$  matrix  $C_\tau$  belong to  $C^1(\bar{\Omega})$ ;

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$$\begin{aligned} 0 < c_{\min} \leq a(x_n), c(x) \leq c_{\max} < \infty, x \in \Omega \\ 0 < c_{\min} Id_{n-1} \leq C_\tau \leq c_{\max} Id_{n-1} < \infty, x \in \Omega; \end{aligned} \quad (2)$$

- $\omega$  is a fixed open set with  $\omega \Subset \Omega^+$ ;
- $\delta, 0 < \delta < H$ , is a real number small enough in order that  $\Omega' \times (0, \delta)$  does not contains entirely  $\omega$ ;
- $\varphi$  is a weight function such that  $\varphi(x) = e^{\lambda\beta(x)}$ ,  $\beta \in \mathcal{C}^0(\bar{\Omega})$ ,  $\lambda > 0$ .

**Note that the functions  $a$  and  $c$  can be discontinuous on  $x_n = 0$ .** Our main result is the Carleman estimate given by

**Theorem 1.** *There exist three strictly positive constants  $C, \lambda_0, s_0$  and a function  $\varphi, \varphi(x) = e^{\lambda\beta(x)}$ , with  $\beta \in C^0(\bar{\Omega})$ , such that*

$$s\lambda^2 \|e^{s\varphi} \varphi^{\frac{1}{2}} \nabla u\|_{L^2(\Omega)}^2 + s^3 \lambda^4 \|e^{s\varphi} \varphi^{\frac{3}{2}} u\|_{L^2(\Omega)}^2 + s\lambda \left( \|e^{s\varphi} \varphi^{\frac{1}{2}} \nabla_\tau u\|_{L^2(S)}^2 + \|e^{s\varphi} \varphi^{\frac{1}{2}} \partial_{x_n} u\|_{L^2(S)}^2 \right) + s^3 \lambda^3 \|e^{s\varphi} \varphi^{\frac{3}{2}} u\|_{L^2(S)}^2 \leq C \left( \|e^{s\varphi} Au\|_{L^2(\Omega)}^2 + s^3 \lambda^4 \|e^{s\varphi} \varphi^{\frac{3}{2}} u\|_{L^2(\omega)}^2 \right) \quad (3)$$

for all  $u \in D(A)$ ,  $\lambda \geq \lambda_0$  and  $s \geq s_0$ .

## 2 Some ideas on the used approach

We shall begin to prove the result in a local case, i.e. in  $\Omega_\delta := \Omega' \times (-\delta, \delta)$ ,  $0 < \delta < H$ , where  $\delta, 0 < \delta < H$ , is a real number small enough in order that  $\Omega' \times (0, \delta)$  does not contain entirely  $\omega$ . In this configuration, the last term of (3) does not exist.

Then, the global estimate (3) in  $\Omega$  is a consequence of works of other authors, by example [5]. We shall give indications.

**We start** from the following estimate which is wellknown by the specialists:

*There exist on  $\Omega_\delta$  a weight function  $x_n \rightarrow \beta(x_n)$ , non decreasing since we assume  $\omega \subset \Omega^+$ , and four strictly positive constants  $C, C', \lambda_0, s_0$  such that*

$$C \left( s\lambda^2 \|\varphi^{\frac{1}{2}} e^{s\varphi} \nabla u\|_{L^2(\Omega_\delta)}^2 + s^3 \lambda^4 \|\varphi^{\frac{3}{2}} e^{s\varphi} u\|_{L^2(\Omega_\delta)}^2 \right) + s\lambda \varphi|_S \left( \int_S [c^2 \beta' |e^{s\varphi} \partial_{x_n} u|^2]_S d\sigma + \int_S |s\lambda \varphi e^{s\varphi} u|_S^2 [c^2 \beta'^3]_S d\sigma \right) \leq C' \|e^{s\varphi} Au\|_{L^2(\Omega_\delta)}^2 + s\lambda \varphi|_S \int_S |e^{s\varphi} \nabla_\tau u|^2 \|[\beta' c a C_\tau]_S\| d\sigma \quad (4)$$

$\forall u \in D(A)$ ,  $\lambda \geq \lambda_0$ ,  $s \geq s_0$  and  $\text{supp } u \subset \bar{\Omega}' \times (-\delta, \delta)$ .

In (4),  $\nabla_\tau$  is the gradient relatively to the horizontal coordinates  $x' = (x_1, \dots, x_{n-1})$  and  $[f]_S(x') := f(x', 0^+) - f(x', 0^-)$  is the jump of the function (resp. matrix)  $f$  across the interface  $S$  in  $L^\infty(S)$ .

So, it is clear that we have to estimate  $s\lambda \varphi|_S \int_S |e^{s\varphi} \nabla_\tau u|^2 \|[\beta' c a C_\tau]_S\| d\sigma$  in order to prove that the left hand side can absorb it.

**In a first step**, we assume that the function  $x_n \rightarrow a(x_n)$  is equal to 1. The introduction of a partition of unity on the interface allows us to recover  $\Omega_\delta$  by small cubes, indexed by  $(j, \ell)$ , in which we approach the tangential operators  $A_\tau := -\nabla_\tau \cdot C_\tau \nabla_\tau$  by operators with constant coefficients in each cube. So, from  $Au = f$  we deduce the sequence of problems

$$\left\{ \begin{array}{l} -\nabla_\tau \cdot (C_\tau^{j,\ell} \nabla_\tau u_{j,\ell}) - c^{j,\ell} \partial_{x_n}^2 u_{j,\ell} = f_{j,\ell} + \tilde{g}_{j,\ell} + \tilde{h}_{j,\ell} + t_{j,\ell}, \\ \text{avec} \\ \tilde{g}_{j,\ell} := (c - c^{j,\ell}) \partial_{x_n}^2 u_{j,\ell}, \\ \tilde{h}_{j,\ell} := [A, \Upsilon_\ell \chi_j] u + (\partial_{x_n} c) \partial_{x_n} u_{j,\ell}, \\ t_{j,\ell} := \nabla_\tau \cdot ((C_\tau - C_\tau^{j,\ell}) \nabla_\tau u_{j,\ell}), \end{array} \right. \quad (5)$$

with the following transmission conditions

$$[u_{j,\ell}]_S = 0, [c^{j,\ell} \partial_{x_n} u_{j,\ell}]_S = [(c^{j,\ell} - c) \partial_{x_n} u_{j,\ell}]_S := \theta_{j,\ell}. \quad (6)$$

By projection on a complete system of eigenfunctions of  $A_\tau$  we arrive to a sequence of ordinary differential equations

$$\begin{aligned} \mu_{j,\ell,k}^2 u_{j,\ell,k} - c^{j,\ell} \partial_{x_n}^2 u_{j,\ell,k} &= f_{j,\ell,k} + \tilde{g}_{j,\ell,k} + \tilde{h}_{j,\ell,k} + t_{j,\ell,k} \\ [u_{j,\ell,k}]_S &= 0, [c^{j,\ell} \partial_{x_n} u_{j,\ell,k}]_S = \theta_{j,\ell,k}. \end{aligned} \quad (7)$$

Two points are crucial: the size of these cubes and the treatment of the operator  $A_\tau$  in the cubes included in a neighborhood of the boundary and the interface at once.

**The second step** concerns the case without the hypothesis  $a(x_n) = 1$ .

### 3 Some comments

According to remaining time we shall compare several recent works ([4], [5],[6], [2]). Each time the trace of the solution  $ue^{s\varphi}$  on the interface is evaluated, and we shall see the limits and advantages of cited works. In our case we evaluate  $u$  multiplied by a constant: the value of the trace of  $\varphi$  on  $S$ . Our method ([1]) allows us to obtain Theorem 1 when the interface  $S$  and  $\partial\Omega$  are transverse. Many questions are open, in particular the case of a parabolic operator with discontinuous coefficients (the first work is [3]).

### References

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