A nonlinear integro-differential equation of earthquake faulting

Shiro Hirano¹

Abstract for RIMS Workshop on "Analysis of inverse problems through partial differential equations and related topics", Jan. 08–10, 2020

Dynamic rupture and slip between two rock masses during an earthquake have been modeled under a framework of an integral equation that represents traction force balance on a fault plane. Assuming that the earth's crust is an infinite homogeneous elastic body with the density and rigidity of unity and its displacement \boldsymbol{u} shows anti-plane deformation (e.g., $\boldsymbol{u}^T = (0, 0, u_3(x_1, x_2, t)))$ for simplicity, the displacement is represented by the double layer potential [1]

$$u_3(x_1, x_2, t) = \int_0^t \int_{\mathbb{R}} D(\xi, \tau) \partial_{x_2} G(x_1 - \xi, x_2, t - \tau) d\xi d\tau,$$
(1)

where $D(x_1,t) := \lim_{\epsilon \to 0} [u_3(x_1, x_2, t)]_{x_2=-\epsilon}^{x_2=+\epsilon}$ is the slip along the fault (= x_1 -axis), and $G(x_1, x_2, t)$ is the fundamental solution of the 2-D wave equation $\partial_t^2 G - \Delta G = \delta(x_1, x_2, t)$ with zero initial condition ($G = \partial_t G = 0$ for $t \leq 0$).

The shear stress $\lim_{x_2\to 0} \partial_{x_2} u_3$ must balance with a change of frictional force on the fault. Many rock experiments have shown that the friction is a nonlinear, monotonically decreasing function of D and/or $V := \partial_t D$; we may write $\sigma = F(D, V)$ [2]. Simultaneously, an empirical law based on seismic observations allows us to assume that D and V are a homogeneous function of degree one and zero, respectively: i.e., $D(x_1, t) = tD(X)$, and $V(x_1, t) = V(X)$, where $X := x_1/(vt)$, and v is the rupture velocity (i.e., extension speed of the support of $D(x_1)$) along the fault. Given the above properties, we derive the following nonlinear integro-differential equation

$$\frac{X}{\sqrt{1 - (vX)^2}} \frac{d}{dX} F(D, V) = \frac{d}{dX} \int_{-1}^{+1} \frac{V(\xi)}{\xi - X} \frac{d\xi}{\pi}$$
(2)

from eq.(1) and exemplify approximate solutions of V for some simplified cases.

References

- [1] Aki, K. & P.G. Richards (1980), Quantitative seismology, 1st edn., Freeman, New York.
- [2] Ohnaka, M. & T. Yamashita (1989), A cohesive zone model for dynamic shear faulting based on experimentally inferred constitutive relation and strong motion source parameters, J. geophys. Res., 94(B4) 4089–4104.

¹Department of Physical Science, College of Science and Engineering, Ritsumeikan University, 1-1-1, Nojihigashi, Kusatsu, Shiga, 525-8577, Japan. E-mail: s-hrn@fc.ritsumei.ac.jp